# Autonomous Helicopter (ALF)



## Contact

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Historic monument conservation: Minster of Freiburg

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#### Basic data all for current airframe

Rotor diameter: Height (min): Width: Length: Weight: Average noise level: Others: 135 cm 41 cm 30 cm approx. 116 cm 4,5 kg with 10 Ah/22,2V accumulator electric drive no Bell-Hiller mechanics





Inspection of power lines

## Mobility

#### all for current airframe



Climbing performance: 12 m/s brushless electric motor Propulsion: Endurance: > 25 min, depending on accumulator Max. speed: 110 km/h 2.5 ka Pavload: Steering: roll/pitch/collective pitch/heading Tether: currently none, but possible Control: waypoint-mode, either programmed or by remote control Manipulator: none

#### **Communication equipment**

Туре:	Digital videolink(s) / several Digital up-/downlinks
Frequency:	2.4 Ghz/5.8 GHz
Number of channels:	spread spectrum for digital up/down/8 channels for videolink
Other:	remote control via 2 independent channels with receiver voting

## **Platform main capabilities**

- all-weather, especially strong wind and ice-built-up conditions
- very manouevrable and fast; very easy handling under full computer control
- steering via waypoint-mode, either programmed or by remote control
- payload up to own empty weight
- can be equipped with carrier phase GPS (RTK)
- system can be adapted to almost any small scale helicopter
- video goggles with main flight data displayed, no further ground station required
- · lots of built-in safety like in-flight system restart, autorotation and simple mechanics
- small package, even smaller for long-range transport
- start-up time out of transport box: 5s (warm), GPS-lock-time (cold)
- quiet and low radar and thermal signature



Inspection of bridges